

## High Sensitivity Micropower Linear Hall-effect Sensor

### Features

- Ratiometric linear hall effect magnetic sensor.
- Analog output with  $V_{REF} / 2$  quiescent offset
- High-impedance output during sleep mode.
- Operates from 2.5V and 5.5V power supplies
- Less than  $1\mu\text{A}$  power consumption in the sleep mode.
- Sensitivity selection  
AW86560DNR: 1.25mV/Gs  
AW86561DNR: 2.50mV/Gs  
AW86562DNR: 5.0mV/Gs  
AW86563DNR: 10.0mV/Gs
- Reference voltage ( $V_{REF}$  pin).
- Temperature-stable quiescent voltage output and sensitivity
- Wide operating temperature range:  $-40^{\circ}\text{C}$  to  $125^{\circ}\text{C}$
- WBDFN 3mm X 2mm X 0.75mm-6L package

### Applications

- Accurate position detection
- Industrial automation robot
- Handheld gaming consoles
- Bluetooth headset
- Medical facility
- Domestic appliance

### General Description

The AW8656XDNR are linear Hall effect IC that respond proportionally to magnetic flux density.. The quiescent output voltage of these devices is 50 % nominal of the ratiometric supply reference voltage applied to the  $V_{REF}$  pin of the device.

The AW8656XDNR consume 2.6 mA of current in the active mode. minimize current consumption to less than  $1\mu\text{A}$  through the addition of a user-selectable sleep mode.

The AW8656XDNR features magnet temperature compensation to counteract how magnets drift for linear performance across a wide  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$  temperature range. Device options for no temperature compensation of magnet drift are also available.

The AW8656XDNR are available in 6 pin DFN and are rated over  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ . The package is available in a lead (Pb)free version.

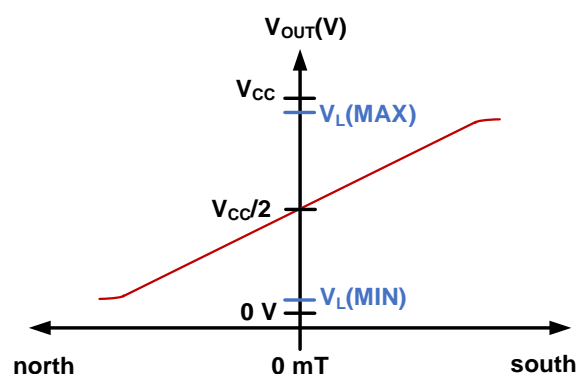


Figure 1  $V_{OUT}$  versus Magnetic Field ( $V_{CC}=V_{REF}$ )

### Typical Application Circuit

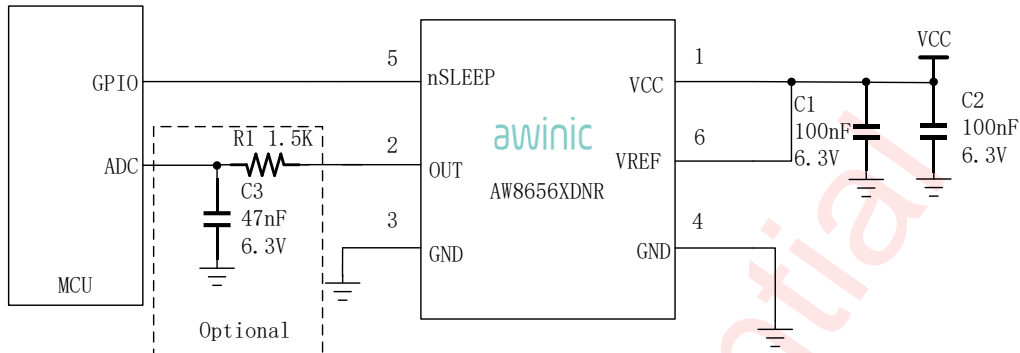
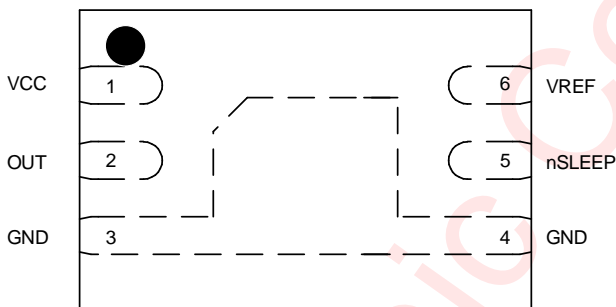


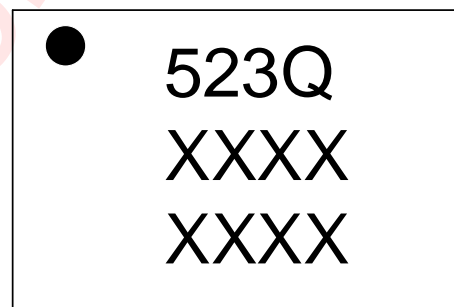
Figure 2 Typical Application Circuit of AW8656XDNR

### Pin Configuration And Top Mark

AW86560DNR  
(Top View)

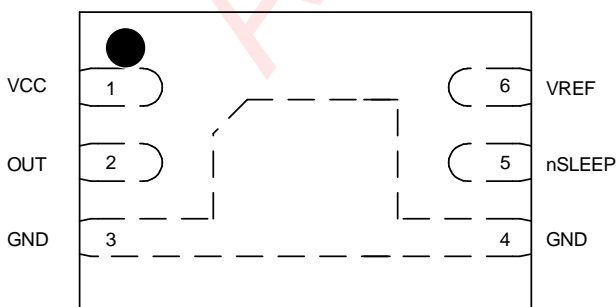


AW86560DNR Marking  
(Top View)

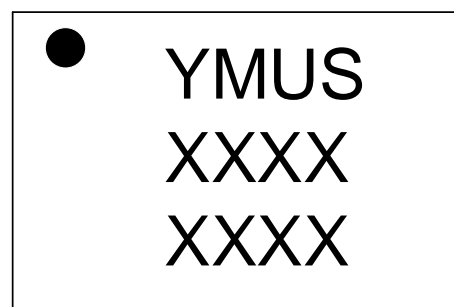


523Q - AW86560DNR  
XXXX/XXXX - Production Tracing Code

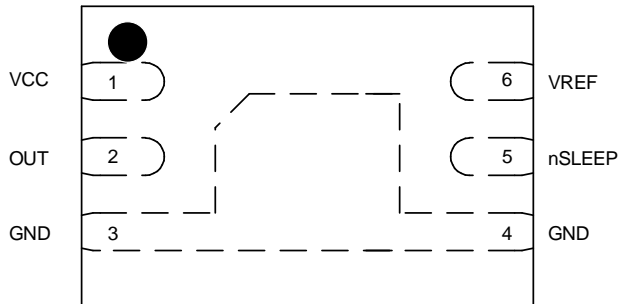
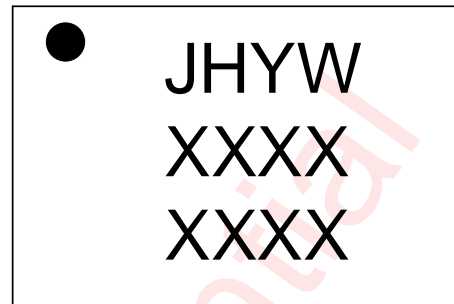
AW86561DNR  
(Top View)



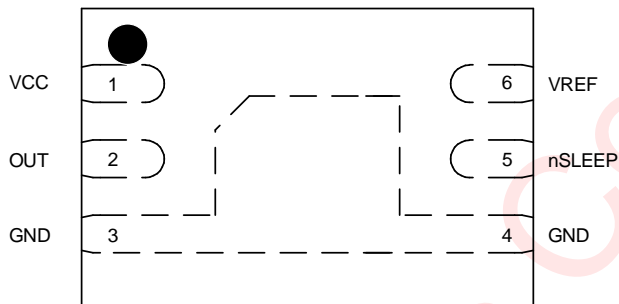
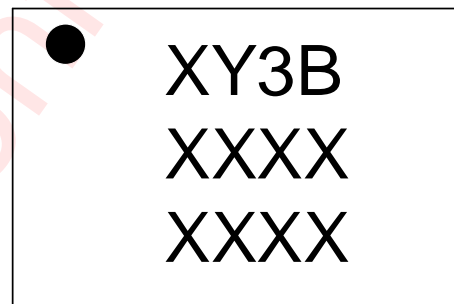
AW86561DNR Marking  
(Top View)



YMUS - AW86561DNR  
XXXX/XXXX - Production Tracing Code

AW86562DNR  
(Top View)AW86562DNR Marking  
(Top View)

JHYW - AW86562DNR  
XXXX/XXXX - Production Tracing Code

AW86563DNR  
(Top View)AW86563DNR Marking  
(Top View)

XY3B - AW86563DNR  
XXXX/XXXX - Production Tracing Code

Figure 3 Pin Configuration And Top Mark

## Pin Definition

No.	NAME	DESCRIPTION
1	VCC	Power Supply
2	OUT	Analog Output
3	GND	Ground
4	GND	Ground
5	nSLEEP	Toggle sleep mode
6	VREF	Supply for ratiometric reference

### AWINIC Linear Hall-effect Sensor Family

Part Number	Sensitivity (mV/Gs, Typ.)	Package
AW86560DNR	1.25	WBDFN 3mm X 2mm X 0.75mm-6L
AW86561DNR	2.5	WBDFN 3mm X 2mm X 0.75mm-6L
AW86562DNR	5.0	WBDFN 3mm X 2mm X 0.75mm-6L
AW86563DNR	10.0	WBDFN 3mm X 2mm X 0.75mm-6L

### Functional Block Diagram

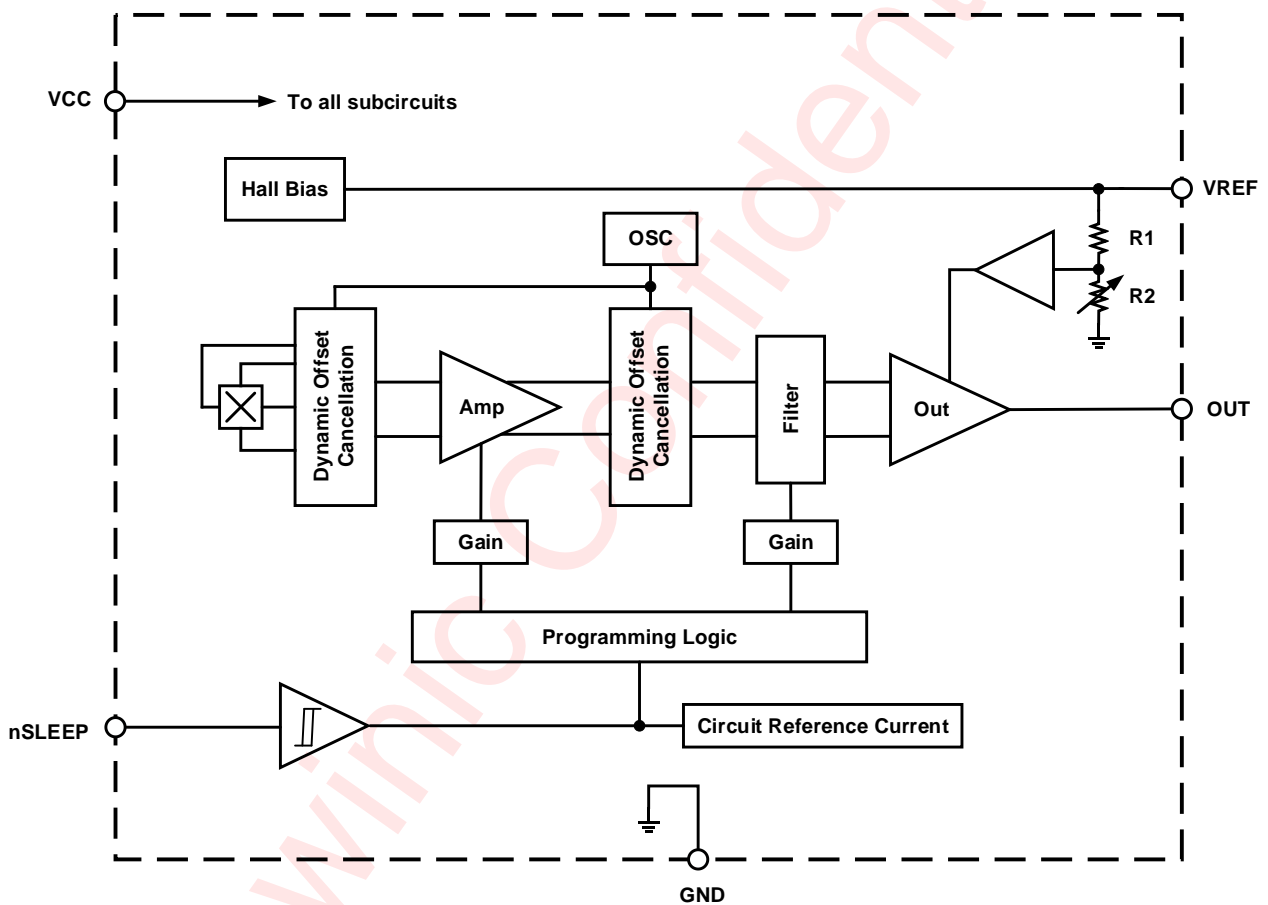


Figure 4 Functional Block Diagram

## Typical Application Circuits

### Device Supply Ratiometry Application Circuit

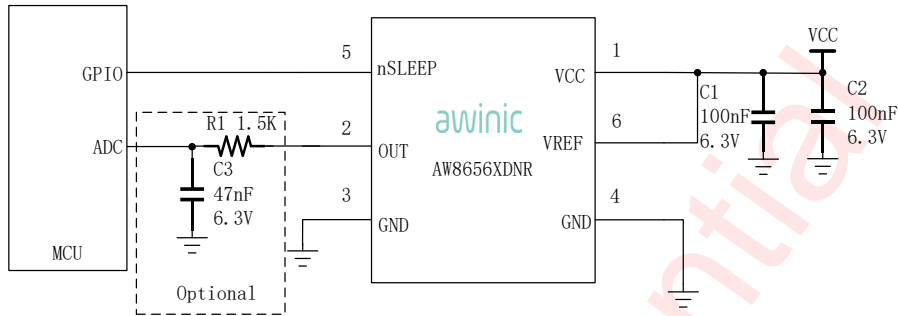


Figure 5 Showing microprocessor-controlled sleep mode and output ratiometric

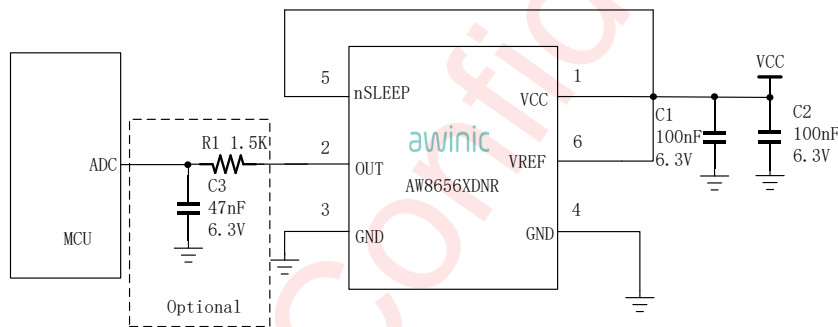


Figure 6 Showing sleep mode disabled and output ratiometric

Figures 5 and 6 present applications where the VCC pin is connected together with the VREF pin of the AW8656XDNR. Both of these pins are connected to VCC. In this case, the device output will be ratiometric with respect to the VCC voltage.

In figure 5, the nSLEEP pin is toggled by the microprocessor; therefore, the device is selectively and periodically toggled between active mode and sleep mode.

In figure 6, the nSLEEP pin is connected to the VCC potential, so the device is always in the active mode.

In both figures, the device output is connected to the input of an A-to-D converter. In this configuration, the converter reference voltage is VCC.

It is strongly recommended that an external bypass capacitor be connected, in close proximity to the AW8656XDNR device, between the VCC and GND pins of the device to reduce both external noise and noise generated by the chopper-stabilization circuits inside of the AW8656XDNR.

## Ordering Information

Part Number	Temperature	Package	Marking	Moisture Sensitivity Level	Environmental Information	Delivery Form
AW86560DNR	-40°C ~ 125°C	WBDFN 3mmX2mm-6L	523Q	MSL1	ROHS+HF	3000 units/ Tape and Reel
AW86561DNR	-40°C ~ 125°C	WBDFN 3mmX2mm-6L	YMUS	MSL1	ROHS+HF	3000 units/ Tape and Reel
AW86562DNR	-40°C ~ 125°C	WBDFN 3mmX2mm-6L	JHYW	MSL1	ROHS+HF	3000 units/ Tape and Reel
AW86563DNR	-40°C ~ 125°C	WBDFN 3mmX2mm-6L	XY3B	MSL1	ROHS+HF	3000 units/ Tape and Reel

## Detailed Function Description

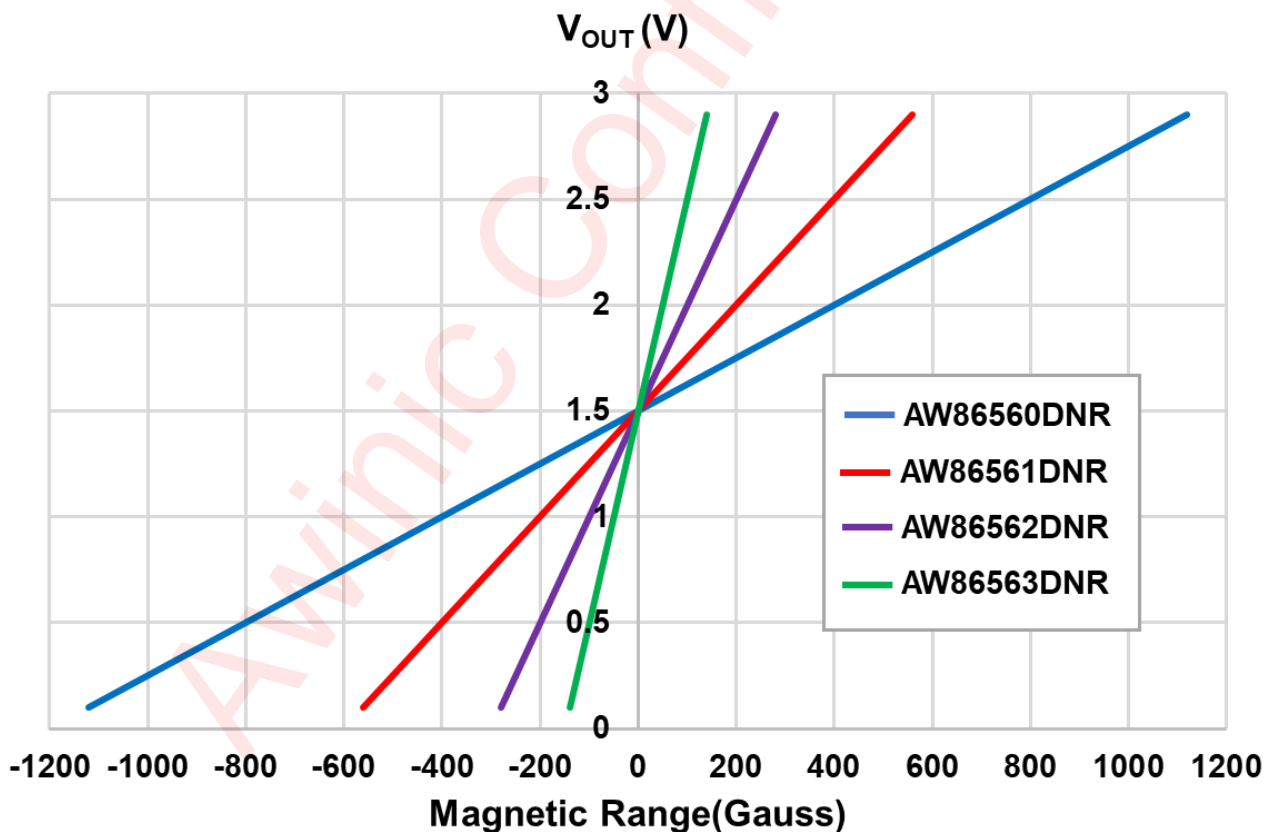


Figure 7  $V_{OUT}$  versus Magnetic Field ( $V_{CC}=V_{REF}=3V$ )

## Absolute Maximum Ratings

PARAMETERS	RANGE
Supply Voltage $V_{CC}$	6V
Reverse-Supply Voltage $V_{RCC}$	-0.1V
Ratiometric Supply Reference Voltage $V_{REF}$	6V
Reverse-Ratiometric Supply Reference Voltage $V_{RREF}$	-0.1V
Logic Supply Voltage $V_{SLEEP}$	6V
Reverse-Logic Supply Voltage $V_{RSLEEP}$	-0.1V
Output Voltage $V_{OUT}$	$V_{CC} + 0.1V$
Reverse-Output Voltage $V_{ROUT}$	-0.1V
Operating Ambient Temperature $T_A$	-40 to 125°C
Junction Temperature $T_J$ (MAX)	150°C
Storage Temperature $T_{stg}$	-65 to 150°C
Lead temperature (soldering 10 seconds)	260°C
ESD Rating <sup>(NOTE2 3)</sup>	
Human Body Model (HMB) ESD capability	±6kV
Charged-device model (CDM) ESD capability	±1.5kV
Latch-up	
Test Condition: JESD78E	+ IT: 200mA - IT: 200mA

**NOTE1:** Conditions out of those ranges listed in "absolute maximum ratings" may cause permanent damages to the device. In spite of the limits above, functional operation conditions of the device should within the ranges listed in "recommended operating conditions". Exposure to absolute-maximum-rated conditions for prolonged periods may affect device reliability.

**NOTE2:** The human body model is a 100pF capacitor discharged through a 1.5kΩ resistor into each pin. Test method: ESDA/JEDEC JS -001-2017.

**NOTE3:** Charge Device Model test method: ESDA/JEDEC JS-002-2018.

## Electrical Characteristics

$T_A = 25^\circ\text{C}$ ,  $V_{CC} = V_{REF} = V_{CCN}$  for typical values (unless otherwise noted)

PARAMETER		TEST CONDITION	MIN	TYP <sup>1</sup>	MAX	UNIT
$V_{CC}$	Supply Voltage		2.5	–	5.5	V
$V_{CCN}$	Nominal Supply Voltage		–	3.0	–	V
$V_{REF}$	Ratiometric Reference Voltage <sup>2</sup>		2.5	–	$V_{CC}$	V
	nSLEEP Input Voltage		–0.1		$V_{CC} + 0.1\text{V}$	V
$V_{INH}$	nSLEEP Input Threshold	For active mode	–	$0.45 \times V_{CC}$	–	V
$V_{INL}$		For sleep mode	–	$0.20 \times V_{CC}$	–	V
$R_{REF}$	Ratiometric Reference Input Resistance	$V_{SLEEP} > V_{INH}$	140	–	–	k $\Omega$
		$V_{SLEEP} < V_{INL}$	–	1	–	M $\Omega$
$f_c$	Chopper Stabilization Chopping Frequency	$V_{CC} = V_{CCN}$	–	200	–	kHz
$I_{CC}$	Supply Current <sup>3</sup>	$V_{SLEEP} < V_{INL}$	–	1	–	$\mu\text{A}$
		$V_{SLEEP} > V_{INH}$	–	2.6	–	mA
$I_{SLEEP}$	nSLEEP Input Current	$V_{SLEEP} = 3\text{V}$	–	1	–	$\mu\text{A}$
$PSR_{VOQ}$	Quiescent Output Power Supply Rejection <sup>4</sup>	$f_{AC} < 1\text{kHz}$	–	-60	–	dB

<sup>1</sup>Typical data are for initial design estimations only, and assume optimum manufacturing and application conditions, such as  $T_A = 25^\circ\text{C}$ . Performance

may vary for individual units, within the specified maximum and minimum limits.

<sup>2</sup>Voltage applied to the VREF pin. Note that the VREF voltage must be less than or equal to  $V_{CC}$ . Degradation in device accuracy will occur with applied voltages of less than 2.5 V.

<sup>3</sup> If the VREF pin is tied to the VCC pin, the supply current would be  $I_{VCC} + V_{REF} / R_{REF}$

<sup>4</sup>  $f_{AC}$  is any ac component frequency that exists on the supply line.

## Output Characteristics

$T_A = 25^\circ\text{C}$ ,  $V_{CC} = V_{REF} = V_{CCN}$  for typical values (unless otherwise noted)

PARAMETER		TEST CONDITION	MIN	TYP <sup>1</sup>	MAX	UNIT	
$V_{OUTH}$	Output Voltage	$B = X$	–	$V_{CC} - 0.1$	–	V	
$V_{OUTL}$	Saturation Limits <sup>2</sup>	$B = -X$	–	0.1	–	V	
$V_{OUTMAX}$	Maximum Voltage Applied to Output	$V_{SLEEP} < V_{INL}$	–	–	$V_{CC} + 0.1$	V	
Sens	Sensitivity <sup>3</sup>	AW86560DNR	$C_{Bypass}=100\text{nF}$	–	1.25	–	mV/Gs
		AW86561DNR		–	2.5	–	mV/Gs
		AW86562DNR		–	5.0	–	mV/Gs
		AW86563DNR		–	10.0	–	mV/Gs
$V_{OUTQ}$	Quiescent Output	$B = 0 \text{ Gs}$	–	$0.5 \times V_{REF}$	–	V	
$R_{OUT}$	Output Resistance <sup>4</sup>	$f_{out} = 1 \text{ kHz}$ , $V_{SLEEP} > V_{INH}$ , Active mode	–	20	–	$\Omega$	
		$f_{out} = 1 \text{ kHz}$ , $V_{SLEEP} < V_{INL}$ , Sleep mode	–	1M	–	$\Omega$	
$R_L$	Output Load Resistance	Output to ground	15	–	–	k $\Omega$	
$C_L$	Output Load Capacitance		–	–	1	nF	
BW	Output Bandwidth	–3 dB point, $V_{CC} = V_{CCN}$ , $V_{OUT} = 1 V_{pp}$ sinusoidal	–	10	–	kHz	
$V_{rms}$	Noise <sup>5</sup>	AW86560DNR	$C_{Bypass}=100\text{nF}$ $R_{filter}=1.5\text{K}\Omega$ $C_{filter}=47\text{nF}$	–	0.48	–	mVrms
		AW86561DNR		–	0.96	–	mVrms
		AW86562DNR		–	2.40	–	mVrms
		AW86563DNR		–	4.25	–	mVrms
$S_{TC}$	Sensitivity temperature compensation for magnets	$-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$	–	0.12	–	%/ $^\circ\text{C}$	
$S_{LE}$	Sensitivity linear error	within the Output Voltage Saturation Range	–	$\pm 1$	–	%	

<sup>1</sup>Typical data are for initial design estimations only, and assume optimum manufacturing and application conditions, such as  $T_A = 25^\circ\text{C}$ . Performance

may vary for individual units, within the specified maximum and minimum limits.

<sup>2</sup>This test requires positive and negative magnetic fields sufficient to swing the output driver between fully OFF and saturated (ON), respectively. The

value of vector X is NOT intended to indicate a range of linear operation.

<sup>3</sup>For  $V_{REF}$  values other than  $V_{REF} = V_{CCN}$ , the sensitivity can be derived from the following equation:  $0.416 \times V_{REF}$ .

<sup>4</sup> $f_{OUT}$  is the output signal frequency

<sup>5</sup>Noise specification includes digital and analog noise.

## Output Timing Characteristics

PARAMETER <sup>1</sup>		TEST CONDITION	MIN	TYP <sup>2</sup>	MAX	UNIT
t <sub>PON</sub>	Power-On Time <sup>3</sup>	T <sub>A</sub> = 25°C	–	40	–	μs
t <sub>POFF</sub>	Power-Off Time <sup>4</sup>	T <sub>A</sub> = 25°C	–	1	–	μs

<sup>1</sup>See figure 10 for explicit timing delays.

<sup>2</sup>Typical data are for initial design estimations only, and assume optimum manufacturing and application conditions, such as T<sub>A</sub> = 25°C. Performance may vary for individual units, within the specified maximum and minimum limits.

<sup>3</sup>Power-On Time is the elapsed time after the voltage on the nSLEEP pin exceeds the active mode threshold voltage, V<sub>INH</sub>, until the time the device output reaches 90% of its value. When the device output is loaded with the maximum capacitance of 1 nF, the Power-On Time range is guaranteed for input nSLEEP pin frequencies less than 10 Hz.

<sup>4</sup>Power-Off Time is the duration of time between when the signal on the nSLEEP pin switches from HIGH to LOW and when I<sub>CC</sub> drops to under 100 μA. During this time period, the output goes into the HIGH impedance state.

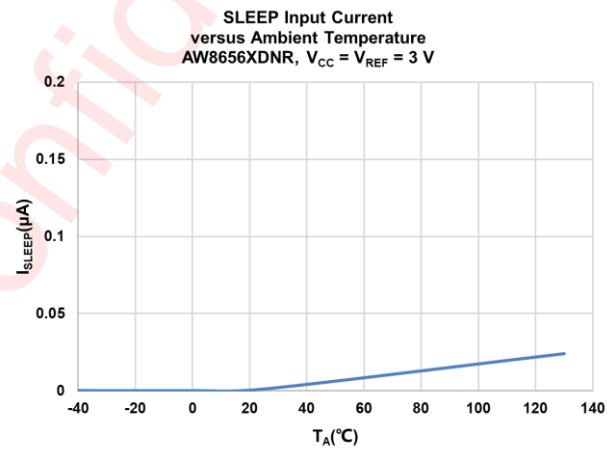
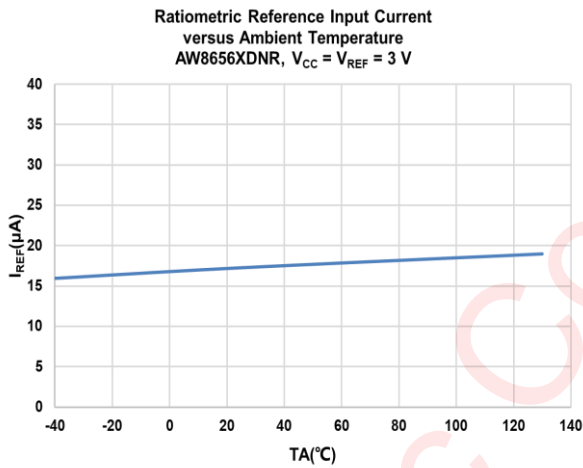
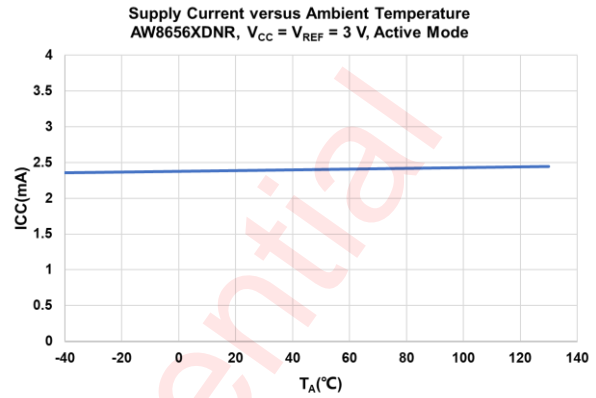
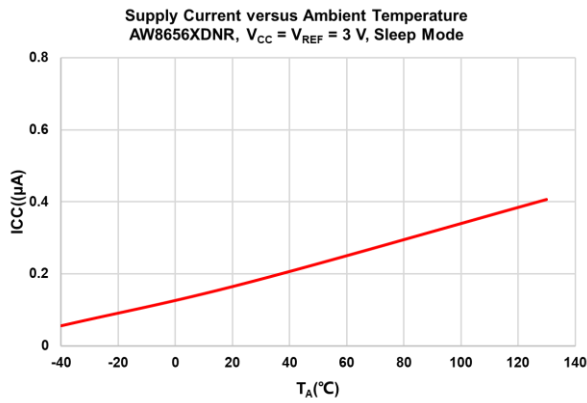
## Magnetic Characteristics

PARAMETER		TEST CONDITION	MIN	TYP*	MAX	UNIT
ΔV <sub>OUTQ(ΔV)</sub>	Ratiometry		–	99.5	–	%
ΔSens(ΔV)	Ratiometry		–	99.5	–	%
Lin+	Positive Linearity		–	99.0	–	%
Lin-	Negative Linearity		–	99.0	–	%
Sym	Symmetry		–	98.0	–	%

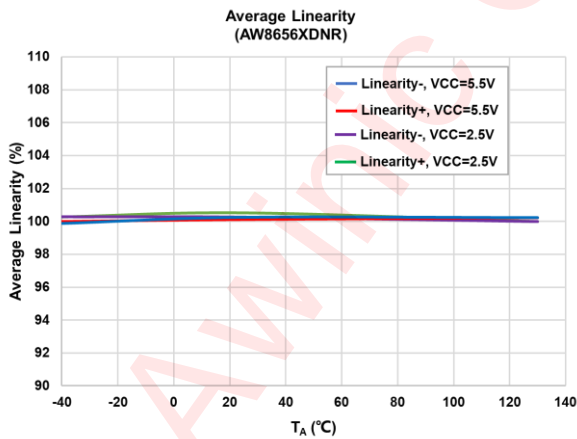
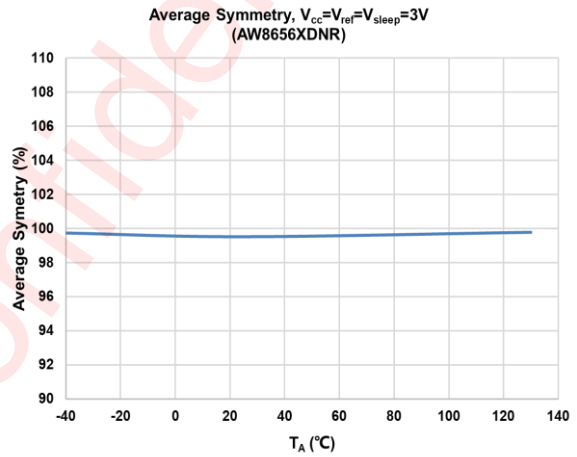
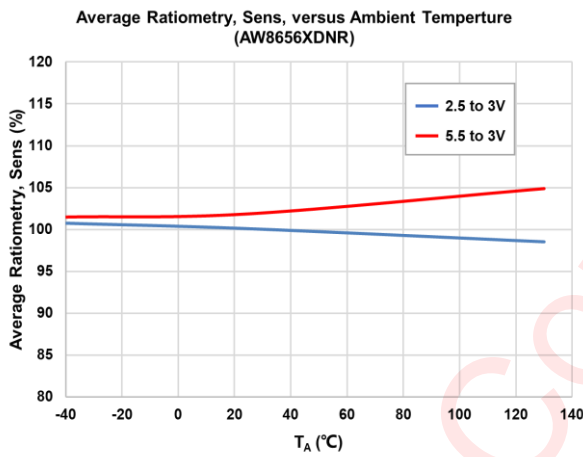
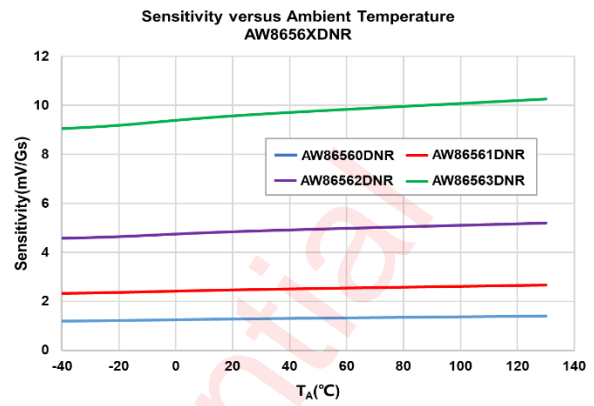
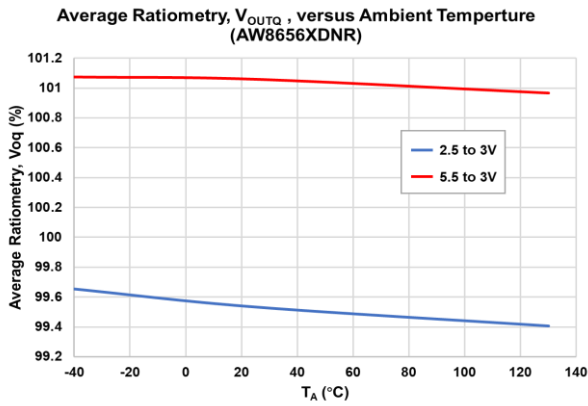
\*Typical data are for initial design estimations only, and assume optimum manufacturing and application conditions, such as T<sub>A</sub> = 25°C. Performance may vary for individual units, within the specified maximum and minimum limits.

## Typical Characteristics

### Electrical Characteristic Data



### Magnetic Characteristic Data



## Characteristics Definitions

**Ratiometric.** The AW8656XDNR devices feature ratiometric output. The quiescent voltage output and sensitivity are proportional to the ratiometric supply reference voltage. The percent ratiometric change in the quiescent voltage output is defined as:

$$\Delta V_{OUTQ(\Delta V)} = \frac{\Delta V_{OUTQ(VREF)} \div \Delta V_{OUTQ(3V)}}{V_{REF} \div 3V} \times 100\% \quad (1)$$

and the percent ratiometric change in sensitivity is defined as:

$$\Delta Sens_{(\Delta V)} = \frac{\Delta Sens_{(VREF)} \div \Delta Sens_{(3V)}}{V_{REF} \div 3V} \times 100\% \quad (2)$$

**Linearity and Symmetry.** The on-chip output stage is designed to provide a linear output with maximum supply voltage of  $V_{CCN}$ . Although application of very high magnetic fields will not damage these devices, it will force the output into a non-linear region. Linearity in percent is measured and defined as:

$$Lin+ = \frac{V_{OUT(+B)} - V_{OUTQ}}{2 \times (V_{OUT(+B/2)} - V_{OUTQ})} \times 100\% \quad (3)$$

$$Lin- = \frac{V_{OUT(-B)} - V_{OUTQ}}{2 \times (V_{OUT(-B/2)} - V_{OUTQ})} \times 100\% \quad (4)$$

and output symmetry as:

$$sym = \frac{V_{OUT(+B)} - V_{OUTQ}}{V_{OUTQ} - V_{OUT(-B)}} \times 100\% \quad (5)$$

The Parameter  $S_{LE}$  defines the linear error as the difference in sensitivity between any positive B values and any negative B values when the output is within the Output Voltage Saturation range.

$$S_{LE} = \frac{sen_+ - sen_-}{0.5 \times (sen_+ + sen_-)} \times 100\% \quad (6)$$

## Detailed Functional Description

AW8656XDNR are low-power Hall effect sensor ICs that are perfect for power sensitive customer applications. The current consumption of these devices is typically 2.6 mA, while the device is in the active mode, and less than 1  $\mu$ A when the device is in the sleep mode. Toggling the logic level signal connected to the nSLEEP pin drives the device into either the active mode or the sleep mode. A logic low sleep signal drives the device into the sleep mode, while a logic high sleep signal drives the device into the active mode.

In the case in which the VREF pin is powered before the VCC pin, the device will not operate within the specified limits until the supply voltage is equal to the reference voltage. When the device is switched from the sleep mode to the active mode, a time defined by  $t_{PON}$  must elapse before the output of the device is valid. The device output transitions into the high impedance state approximately  $t_{POFF}$  seconds after a logic low signal is applied to the nSLEEP pin (see Figure 8).

If possible, it is recommended to power-up the device in the sleep mode. However, if the application requires that the device be powered on in the active mode, then a 10 k $\Omega$  resistor in series with the nSLEEP pin is recommended. This resistor will limit the current that flows into the nSLEEP pin if certain semiconductor junctions become forward biased before the ramp up of the voltage on the VCC pin. Note that this current limiting resistor is not required if the user connects the nSLEEP pin directly to the VCC pin. The same precautions are advised if the device supply is powered-off while power is still applied to the nSLEEP pin.

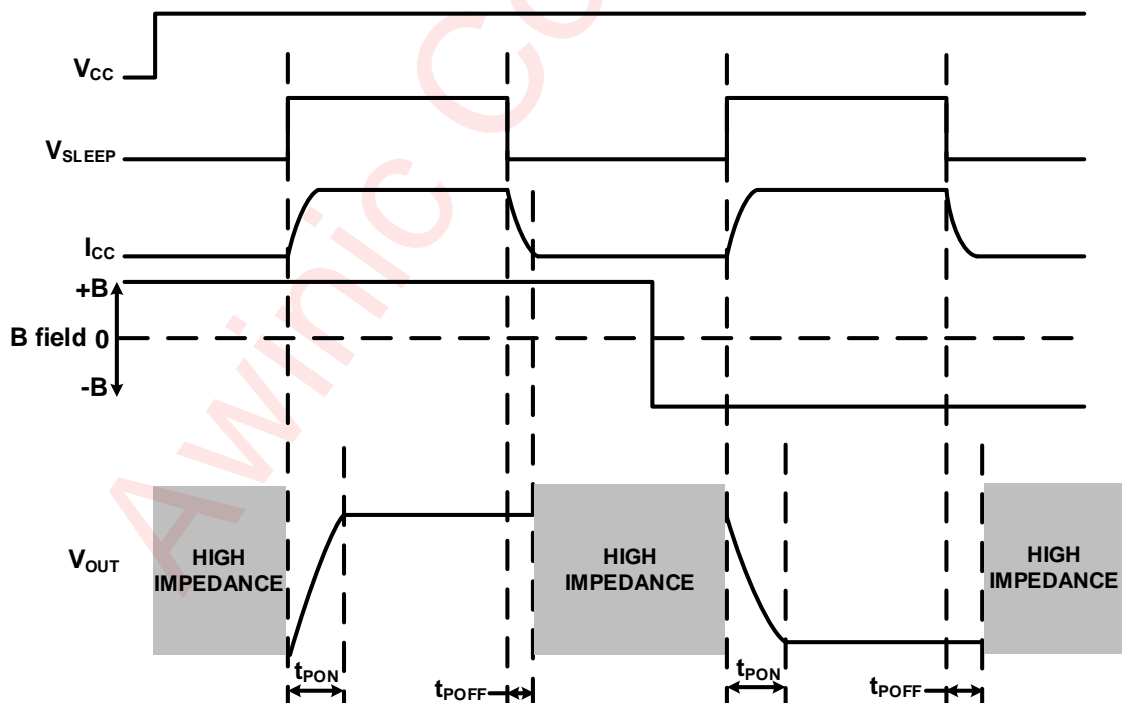
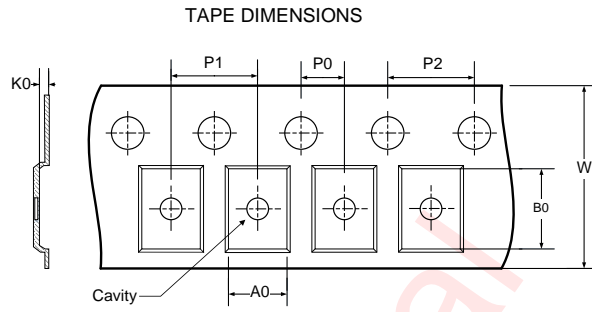
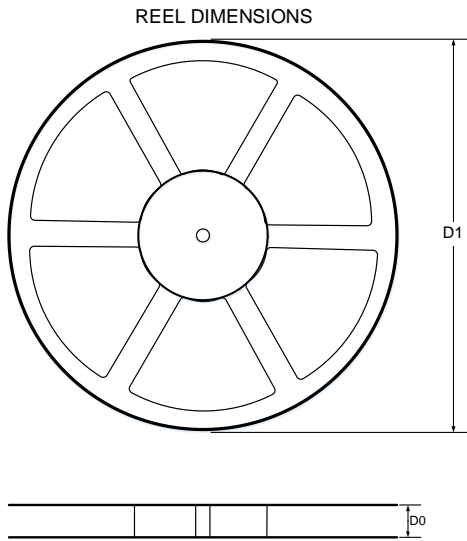


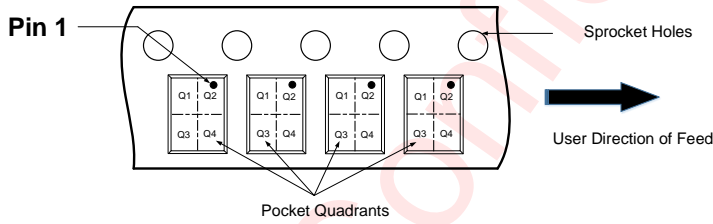
Figure 8 AW8656XDNR Timing Diagram

## Tape And Reel Information



A0: Dimension designed to accommodate the component width  
 B0: Dimension designed to accommodate the component length  
 K0: Dimension designed to accommodate the component thickness  
 W: Overall width of the carrier tape  
 P0: Pitch between successive cavity centers and sprocket hole  
 P1: Pitch between successive cavity centers  
 P2: Pitch between sprocket hole  
 D1: Reel Diameter  
 D0: Reel Width

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



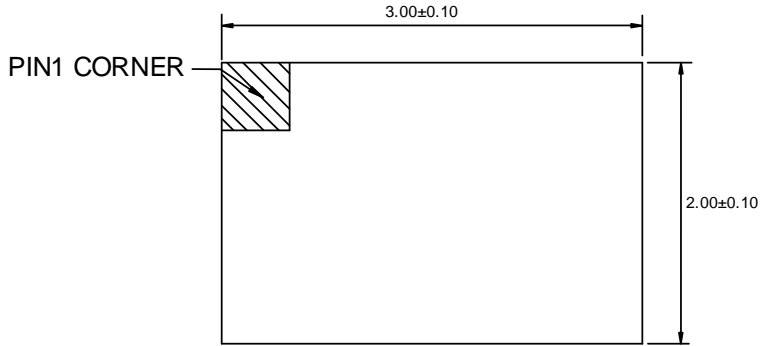
Note: The above picture is for reference only. Please refer to the value in the table below for the actual size

DIMENSIONS AND PIN1 ORIENTATION

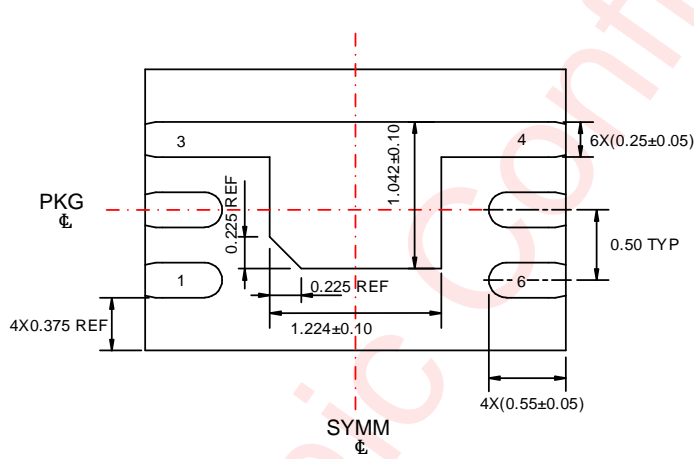
D1 (mm)	D0 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P0 (mm)	P1 (mm)	P2 (mm)	W (mm)	Pin1 Quadrant
178	8.4	2.3	3.2	1	2	4	4	8	Q2

All dimensions are nominal

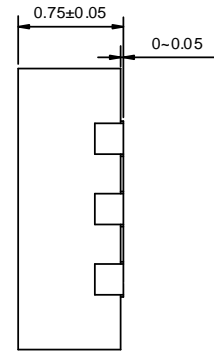
Package Description



Top View



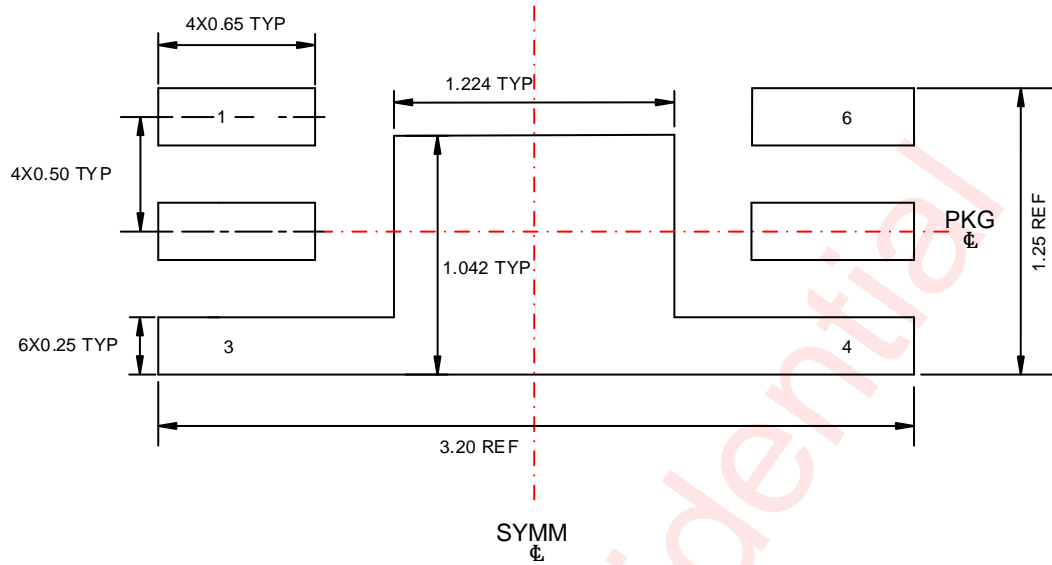
Bottom View



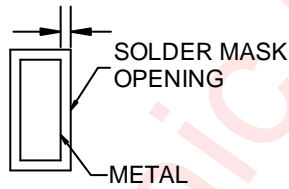
Side View

Unit: mm

Land Pattern Data

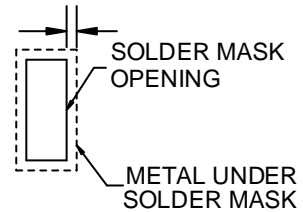


0.05 MAX  
All AROUND



NON SOLDER MASK DEFINED

0.05 MIN  
All AROUND



SOLDER MASK DEFINED

Unit: mm

## Revision History

Version	Date	Change Record
V1.0	Nov 2022	Initial release
V1.1	Oct. 2024	Added Temperature Compensation for Magnets and Change Noise Data

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